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netclient.c:

/* Make the necessary includes and set up the variables. */ }

#include <sys/types.h>
#include <sys/socket.h>
#include <stdio.h>
#include <stdlib.h>
#include <netinet/in.h>
#include <arpa/inet.h>
#include <unistd.h>

int
main ()
{
    int sockfd;
    socklen_t len;
    struct sockaddr_in address;
    int result;
    char ch = 'A';

    /* Create a socket for the client. */
    sockfd = socket (AF_INET, SOCK_STREAM, 0);

    /* Name the socket, as agreed with the server. */

    address.sin_family = AF_INET;
    address.sin_addr.s_addr = inet_addr ("127.0.0.1");
    address.sin_port = htons (9734);
    len = sizeof (address);

    /* Now connect our socket to the server's socket. */

    result = connect (sockfd, (struct sockaddr *) &address,
len);

    if (result == -1)
    {
        perror ("oops: netclient");
        exit (1);
    }

    /* We can now read/write via sockfd. */

    write (sockfd, &ch, 1);
    read (sockfd, &ch, 1);
    printf ("char from server = %c\n", ch);
    close (sockfd);
    exit (0);
}

server1.c:

#include <sys/types.h>
#include <sys/socket.h>
#include <stdio.h>
#include <netinet/in.h>
#include <signal.h>
#include <unistd.h>

int
main ()
{
    int server_sockfd, client_sockfd;
    socklen_t server_len, client_len;
    struct sockaddr_in server_address;
    struct sockaddr_in client_address;

    server_sockfd = socket (AF_INET, SOCK_STREAM, 0);

    server_address.sin_family = AF_INET;
    server_address.sin_addr.s_addr = htonl (INADDR_ANY);
    server_address.sin_port = htons (9734);
    server_len = sizeof (server_address);
    bind (server_sockfd, (struct sockaddr *)
&server_address, server_len);

    /* Create a connection queue and wait for clients. */

    listen (server_sockfd, 5);

    while (1)
    {
        char ch;

        printf ("server waiting\n");

        /* Accept connection. */

        client_len = sizeof (client_address);
        client_sockfd = accept (server_sockfd,
(struct sockaddr *)
&client_address,
&client_len);

        /* We can now read/write to the client on
client_sockfd.           The five second delay is just for this
demonstration. */

        read (client_sockfd, &ch, 1);
        sleep (5);
        ch++;
        write (client_sockfd, &ch, 1);
    }
}

fork1.c:

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <errno.h>

int
main ()
{
    pid_t res;
    int status;
    res = fork ();
    if (res == 0)
    {
        printf ("Hello from child\n");
        sleep (1);
        exit (1);
    }
    if (res == -1)
        perror ("fork");
    wait (&status);
    if (WIFEXITED (status))
        printf ("Child exited normally with exit code %d\n",
WEXITSTATUS (status));
    else
        printf ("Child exited abnormally\n");
    exit (0);
}

fork2.c:

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <errno.h>

int
main ()
{
    pid_t res;
    int status;
    res = fork ();
    if (res == 0)
    {
        printf ("Hello from child\n");
        sleep (1);
        abort ();
    }
    if (res == -1)
        perror ("fork");
    wait (&status);
    if (WIFEXITED (status))
        printf ("Child exited normally with exit code %d\n",
WEXITSTATUS (status));
    else
        printf ("Child exited abnormally\n");
    exit (0);
}

fork3.c:

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <errno.h>

int
main ()
{
    pid_t res;
    int i;
    res = fork ();
    if (res == 0)
    {
        for (i = 0; i < 200; ++i)
        {
            printf ("Hello # %d from child\n", i);
        }
        abort ();
    }
    if (res == -1)
        perror ("fork");
    for (i = 0; i < 200; ++i)
    {
        printf ("Hello # %d from parent\n", i);
        sleep (1);
    }
    exit (0);
}

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}

fork4.c:

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <errno.h>

int
main ()
{
    pid_t res;
    int status;
    int i;
    res = fork ();
    if (res == 0)
    {
        for (i = 0; i < 200; ++i)
            printf ("Hello #%d from child\n", i);
        abort ();
    };
    if (res == -1)
        perror ("fork");
    for (i = 0; i < 200; ++i)
    {
        printf ("Hello #%d from parent\n", i);
        if (waitpid (res, &status, WNOHANG) == res)
            printf ("Child exited\n");
        sleep (1);
    };
    exit (0);
}

fork5.c:

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <errno.h>

void
childsignal (int what)
{
    pid_t v;
    int old_errno = errno;
    printf ("New signal\n");
    while ((v = waitpid (-1, NULL, WNOHANG)) != 0
           && !(v == -1 && errno != EINTR))
        printf ("%d\n", v);
    if (v == -1)
        perror ("waitpid");
    printf ("Signal exit\n");
    errno = old_errno;
}

int
main ()
{
    int i;
    struct sigaction sig;
    sig.sa_handler = childsignal;
    sigemptyset (&sig.sa_mask);
    sig.sa_flags = SA_NOCLDSTOP;
    sigaction (SIGCHLD, &sig, NULL);
    for (i = 0; i < 200; i++)
    {
        pid_t res;
        printf ("Starting child #%d\n", i);
        res = fork ();
        if (res == 0)
        {
            sleep (5);
            exit (i + 1);
        };
        if (res == -1)
            perror ("fork");
    };
    for (i = 0; i < 360; i++)
        sleep (1);
    exit (0);
}

fork6.c:

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <errno.h>

int
main ()
{
    int i;
    signal (SIGCHLD, SIG_IGN);
    for (i = 0; i < 200; i++)
    {
        pid_t res;
        printf ("Starting child #%d\n", i);
        res = fork ();
        if (res == 0)
        {
            sleep (5);
            exit (i + 1);
        };
        if (res == -1)
            perror ("fork");
    };
    for (i = 0; i < 360; i++)
        sleep (1);
    exit (0);
}

server2.c:

#include <sys/types.h>
#include <sys/socket.h>
#include <stdio.h>
#include <stdlib.h>
#include <netinet/in.h>
#include <signal.h>
#include <unistd.h>

int
main ()
{
    int server_sockfd, client_sockfd;
    socklen_t server_len, client_len;
    struct sockaddr_in server_address;
    struct sockaddr_in client_address;
    server_sockfd = socket (AF_INET, SOCK_STREAM, 0);

    server_address.sin_family = AF_INET;
    server_address.sin_addr.s_addr = htonl (INADDR_ANY);
    server_address.sin_port = htons (9734);
    server_len = sizeof (server_address);
    bind (server_sockfd, (struct sockaddr *) &server_address, server_len);

    /* Create a connection queue, ignore child exit
details and wait for clients. */

    listen (server_sockfd, 5);
    signal (SIGCHLD, SIG_IGN);

    while (1)
    {
        char ch;
        printf ("server waiting\n");
        /* Accept connection. */
        client_len = sizeof (client_address);
        client_sockfd = accept (server_sockfd,
                               (struct sockaddr *) &client_address,
                               &client_len);
        /* Fork to create a process for this client
and perform a test to see
whether we're the parent or the child.
*/
        if (fork () == 0)
        {
            /* If we're the child, we can now
read/write to the client on client_sockfd.
The five second delay is just
for this demonstration. */
            read (client_sockfd, &ch, 1);
            sleep (5);
            ch++;
            write (client_sockfd, &ch, 1);
            close (client_sockfd);
            exit (0);
        }
        /* Otherwise, we must be the parent and our
work for this client is finished. */
        else
        {
            close (client_sockfd);
        }
    }
}

eintrs.c:

#include <sys/types.h>
#include <sys/socket.h>
#include <stdio.h>
#include <netinet/in.h>
#include <signal.h>
#include <unistd.h>
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int main ()
{
    ssize_t count;
    char buffer[1024 * 1024];
    int server_sockfd, client_sockfd;
    socklen_t server_len, client_len;
    struct sockaddr_in server_address;
    struct sockaddr_in client_address;

    server_sockfd = socket (AF_INET, SOCK_STREAM, 0);

    server_address.sin_family = AF_INET;
    server_address.sin_addr.s_addr = htonl (INADDR_ANY);
    server_address.sin_port = htons (9734);
    server_len = sizeof (server_address);
    bind (server_sockfd, (struct sockaddr *) &server_address, server_len);
    &server_address, server_len);

    /* Create a connection queue and wait for clients. */

    listen (server_sockfd, 5);
    printf ("server waiting\n");

    /* Accept connection. */

    client_len = sizeof (client_address);
    client_sockfd = accept (server_sockfd,
                           (struct sockaddr *) &client_address,
                           &client_len);

    while (1)
    {
        count = read (client_sockfd, buffer, 1024 *
1024);
        printf ("Read %d bytes\n", count);
    }
}

eintrc.c:

/* Make the necessary includes and set up the variables. */

#include <sys/types.h>
#include <sys/socket.h>
#include <stdio.h>
#include <stdlib.h>
#include <netinet/in.h>
#include <arpa/inet.h>
#include <unistd.h>
#include <signal.h>

void alarmhandler (int s)
{
    signal (SIGALRM, alarmhandler);
    alarm (1);
}

int main ()
{
    int sockfd;
    socklen_t len;
    struct sockaddr_in address;
    int result;
    ssize_t count;
    char buffer[1024 * 1024];
    signal (SIGALRM, alarmhandler);
    alarm (1);

    /* Create a socket for the client. */

    sockfd = socket (AF_INET, SOCK_STREAM, 0);

    /* Name the socket, as agreed with the server. */

    address.sin_family = AF_INET;
    address.sin_addr.s_addr = inet_addr ("127.0.0.1");
    address.sin_port = htons (9734);
    len = sizeof (address);

    /* Now connect our socket to the server's socket. */

    result = connect (sockfd, (struct sockaddr *) &address,
len);

    if (result == -1)
    {
        perror ("oops: eintrc");
        exit (1);
    }

    /* We can now read/write via sockfd. */
    while (1)
    {

        count = write (sockfd, buffer, 1024 * 1024);
        if (count == -1)
            perror ("write");
        else
            printf ("Wrote %d bytes\n", count);
    }
}

threadsafe1.c:

#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

char *
unsafe_itoa (int number)
{
    static char buf[16];
    int i = 0, j;
    do
    {
        buf[i++] = number % 10 + '0';
        number /= 10;
    }
    while (number);
    buf[i] = 0;
    for (j = 0; j < i / 2; j++)
    {
        char c = buf[j];
        buf[j] = buf[i - j - 1];
        buf[i - j - 1] = c;
    };
    return buf;
}

void *
thread (void *param)
{
    int start = *((int *) (param));
    int i;
    printf ("Hello from thread %d\n", start);
    for (i = 0; i < 10000; i++)
        printf ("%d %s\n", i + start, unsafe_itoa (i +
start));
    pthread_exit (param);
}

int
main (int argc, char *argv[])
{
    pthread_t t1, t2;
    pthread_attr_t attr;
    int a, b;
    void *retval;
    a = 0;
    pthread_attr_init (&attr);
    pthread_create (&t1, &attr, thread, &a);
    if (argc > 1)
    {
        b = 10000;
        pthread_create (&t2, &attr, thread, &b);
        pthread_join (t2, &retval);
    };
    pthread_join (t1, &retval);
    exit (0);
}

threadsafe2.c:

#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

char *
safe_itoa (int number, char *buf)
{
    int i = 0, j;
    do
    {
        buf[i++] = number % 10 + '0';
        number /= 10;
    }
    while (number);
    buf[i] = 0;
    for (j = 0; j < i / 2; j++)
    {
        char c = buf[j];
        buf[j] = buf[i - j - 1];
        buf[i - j - 1] = c;
    };
    return buf;
}

void *
thread (void *param)
{
    char buf[16];
    int start = *((int *) (param));
    int i;
    printf ("Hello from thread %d\n", start);
    for (i = 0; i < 10000; i++)
        printf ("%d %s\n", i + start, safe_itoa (i +
start, buf));
    pthread_exit (param);
}

int
main (int argc, char *argv[])
{
    pthread_t t1, t2;
    pthread_attr_t attr;
    int a, b;

```

```

void *retval;
a = 0;
pthread_attr_init (&attr);
pthread_create (&t1, &attr, thread, &a);
if (argc > 1)
{
    b = 10000;
    pthread_create (&t2, &attr, thread, &b);
    pthread_join (t2, &retval);
};
pthread_join (t1, &retval);
exit (0);
}

threadsafe3.c:

#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

char *
unsafe_itoa (int number)
{
    static char buf[16];
    int i = 0, j;
    do
    {
        buf[i++] = number % 10 + '0';
        number /= 10;
    } while (number);
    buf[i] = 0;
    for (j = 0; j < i / 2; j++)
    {
        char c = buf[j];
        buf[j] = buf[i - j - 1];
        buf[i - j - 1] = c;
    };
    return buf;
}

pthread_mutex_t itoa_mutex;

void *
thread (void *param)
{
    int start = *((int *) (param));
    int i;
    printf("Hello from thread %d\n", start);
    for (i = 0; i < 10000; i++)
    {
        pthread_mutex_lock(&itoa_mutex);
        printf ("%d %s\n", i + start, unsafe_itoa (i +
start));
        pthread_mutex_unlock(&itoa_mutex);
    }
    pthread_exit (param);
}

int
main (int argc, char *argv[])
{
    pthread_t t1, t2;
    pthread_attr_t attr;
    int a, b;
    void *retval;
    a = 0;
    pthread_mutex_init(&itoa_mutex,NULL);
    pthread_attr_init (&attr);
    pthread_create (&t1, &attr, thread, &a);
    if (argc > 1)
    {
        b = 10000;
        pthread_create (&t2, &attr, thread, &b);
        pthread_join (t2, &retval);
    };
    pthread_join (t1, &retval);
    pthread_mutex_destroy(&itoa_mutex);
    exit (0);
}

threadsafe4.c:

#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

int c;

void * thread (void *param)
{
    int i;
    for (i = 0; i < 10000; i++)
    {
        c=c*123413123+7;;
    }
    pthread_exit (param);
}

int main (int argc, char *argv[])
{
    pthread_t t1, t2;
    pthread_attr_t attr;
    int a, b;
    void *retval;
    a = 0;
    pthread_attr_init (&attr);
    pthread_create (&t1, &attr, thread, &a);
    if (argc > 1)
    {
        b = 10000;
        pthread_create (&t2, &attr, thread, &b);
        pthread_join (t2, &retval);
    };
    pthread_join (t1, &retval);
    pthread_mutex_destroy(&itoa_mutex);
    printf("c=%d\n",c);
    exit (0);
}

a = 0;
pthread_attr_init (&attr);
pthread_create (&t1, &attr, thread, &a);
if (argc > 1)
{
    b = 10000;
    pthread_create (&t2, &attr, thread, &b);
    pthread_join (t2, &retval);
}
    pthread_join (t1, &retval);
    printf("c=%d\n",c);
    exit (0);
}

threadsafe5.c:

#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

int c;

pthread_mutex_t itoa_mutex;

void *
thread (void *param)
{
    int i;
    for (i = 0; i < 10000; i++)
    {
        pthread_mutex_lock(&itoa_mutex);
        c=c*123413123+7;;
        pthread_mutex_unlock(&itoa_mutex);
    }
    pthread_exit (param);
}

int
main (int argc, char *argv[])
{
    pthread_t t1, t2;
    pthread_attr_t attr;
    int a, b;
    void *retval;
    a = 0;
    pthread_mutex_init(&itoa_mutex,NULL);
    pthread_attr_init (&attr);
    pthread_create (&t1, &attr, thread, &a);
    if (argc > 1)
    {
        b = 10000;
        pthread_create (&t2, &attr, thread, &b);
        pthread_join (t2, &retval);
    };
    pthread_join (t1, &retval);
    pthread_mutex_destroy(&itoa_mutex);
    printf("c=%d\n",c);
    exit (0);
}

threadsafe6.c:

#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>

volatile int c;

pthread_mutex_t itoa_mutex;

void *
thread (void *param)
{
    int i;
    for (i = 0; i < 10000; i++)
    {
        pthread_mutex_lock(&itoa_mutex);
        c=c*123413123+7;;
        pthread_mutex_unlock(&itoa_mutex);
    }
    pthread_exit (param);
}

int
main (int argc, char *argv[])
{
    pthread_t t1, t2;
    pthread_attr_t attr;
    int a, b;
    void *retval;
    a = 0;
    pthread_mutex_init(&itoa_mutex,NULL);
    pthread_attr_init (&attr);
    pthread_create (&t1, &attr, thread, &a);
    if (argc > 1)
    {
        b = 10000;
        pthread_create (&t2, &attr, thread, &b);
        pthread_join (t2, &retval);
    };
    pthread_join (t1, &retval);
    pthread_mutex_destroy(&itoa_mutex);
    printf("c=%d\n",c);
    exit (0);
}

```